



DATA SHEET

SV1D Direct-Attach

SerDes Module

D SERIES





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Introduction

OVERVIEW

The SV1D Direct-Attach SerDes Module is a versatile, high-performance instrument that creates a new category of tool for high-speed digital product engineering teams. It integrates multiple technologies to enable the self-contained test and measurement of complex SerDes interfaces such as PCI Express Gen 3, MIPI M-PHY, Thunderbolt, or USB3. Coupled with a seamless, easy-to-use development environment, this tool enables product engineers with widely varying skills to efficiently work with and develop SerDes verification algorithms. The SV1D mounts directly on an application or test board without cables. It contains 8 independent stimulus generation ports, 8 independent capture and measurement ports and various clocking, synchronization, and lane-expansion capabilities. It has been designed specifically to address the growing need of a parallel, system-oriented test methodology while offering world-class signal-integrity features such as jitter injection and jitter measurement.

With a small footprint, an extensive signal-integrity feature set, and an exceptionally powerful software development environment, the SV1D is not only suitable for signal-integrity verification engineers that perform traditional characterization tasks, but it is also ideal for FPGA developers and software developers who need rapid turnaround signal verification tools or hardware-software interoperability confirmation tools. The SV1D integrates state of the art functions such as digital data capture, bit error rate measurement, clock recovery, jitter decomposition and jitter generation.

KEY BENEFITS

- True parallel bit-error-rate measurement across 8 lanes
- Fully-synthesized integrated jitter injection on all lanes
- Fully-automated integrated jitter testing on all lanes
- Optimized pattern generator rise-time for receiver stress test applications
- Flexible pre-emphasis and equalization
- Flexible loopback support per lane
- Hardware clock recovery per lane
- State of the art programming environment based on the highly intuitive Python language
- Integrated device control through SPI, I2C, or JTAG
- Reconfigurable, protocol customization (on request)



- Python language
- Single-ended or differential low-speed digital I/O for test control
- Reconfigurable, protocol customization (on request)

APPLICATIONS

Parallel PHY validation of serial bus standards such as:

- PCI Express (PCIe)
- UHS-2
- MIPI M-PHY
- CPRI
- USB

- HDMI
- Thunderbolt
- XAUI
- JESD204B
- SATA

Interface test of electrical/optical media such as:

- Backplane
- Cable
- CFP MSA, SFP MSA, SFP+ MSA

Plug-and-play system-level validation such as:

- PCI Express
- DisplayPort sink/source
- MIPI M-PHY

Timing verification:

- PLL transfer function measurement
- Clock recovery bandwidth verification
- Frequency ppm offset characterization

Mixed-technology applications:

- High-speed ADC and DAC (JESD204) data capture and/or synthesis
- FPGA-based system development



Channel and device emulation

Features

MULTI-LANE LOOPBACK

The SV1D is the only bench-top tool that offers instrument-grade loopback capability on all differential lanes. The loopback capability of the SV1D includes:

- Retiming of data for the purpose of decoupling DUT receiver performance from DUT transmitter performance
- Arbitrary jitter or voltage swing control on loopback data

Figure 1 shows two common loopback configurations that can be used with the SV1D. In the first configuration, a single DUT's transmitter and receiver channels are connected through the SV1D. In the second configuration, arbitrary pattern testing can be performed on an end-to-end communications link. The SV1D is used to pass data through from a traffic generator (such as an endpoint on a real system board) to the DUT while stressing the DUT receiver with jitter, skew, or voltage swing.

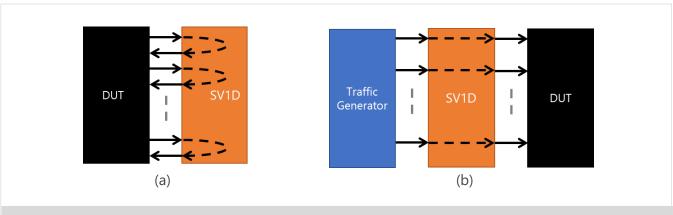
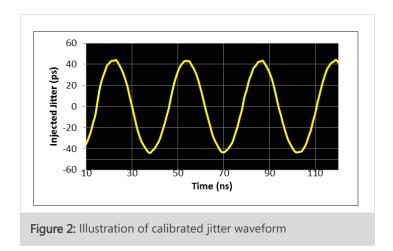


Figure 1: Illustration of loopback applications

MULTIPLE SOURCE JITTER INJECTION

The SV1D can generate calibrated jitter stress on any data pattern and any output lane configuration. Sinusoidal jitter injection is calibrated in the time and frequency domain to generate high-purity stimulus signals as shown in Figure 2.





The jitter injection feature is typically exploited to perform automated jitter tolerance testing as shown in the example in Figure 3. As is the case for other features in the SV1D Direct-Attach SerDes Module, jitter tolerance testing is conducted in parallel across all lanes. For advanced applications, the SV1D also includes RJ injection and a third-source arbitrary waveform jitter synthesizer.

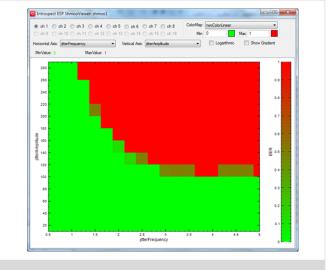


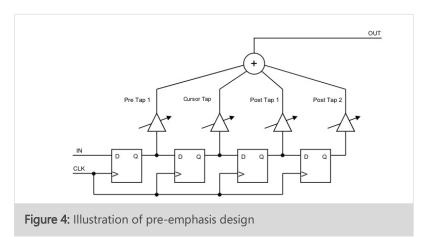
Figure 3: Illustration of calibrated jitter waveform



PRE-EMPHASIS GENERATION

Conventionally offered as a separate instrument, per-lane pre-emphasis control is integrated on the 8-lane SV1D tester. The user can individually set the transmitter pre-emphasis using a built-in Tap structure. Pre-emphasis allows the user to optimize signal characteristics at the DUT input pins.

Each transmitter in the SV1D implements a discrete-time linear equalizer as part of the driver circuit. An illustration of such equalizer is shown in Figure 4 and sample synthesized waveform shapes are shown in Figure 5.



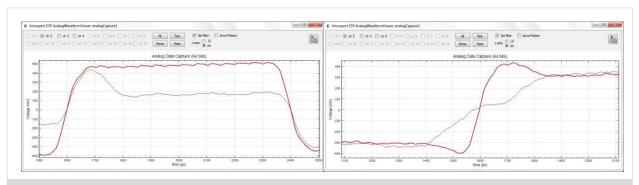
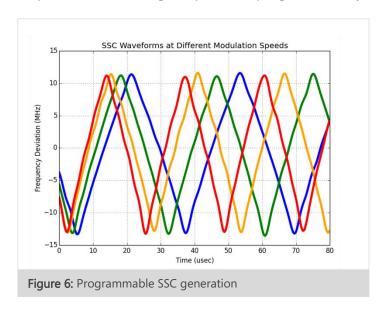


Figure 5: Illustration of multiple waveform shapes that can be synthesized using the pre-emphasis function of the SV1D.



PROGRAMMABLE SSC GENERATION AND FREQUENCY SYNTHESIS

The SV1D incorporates precision frequency synthesis technology that allows for the generation of programmable SSC waveforms at any data rate. The SSC waveforms are superimposed on the pattern generator outputs, and they coexist with other jitter injection sources of the SV1D. Thus, a truly complete jitter cocktail can be produced for the most thorough receiver validation. Figure 6 illustrates the SSC capability of the SV1D. In the figure, the SV1D is programmed to synthesize four slightly different modulation frequencies showcasing the precision programmability of the tool.

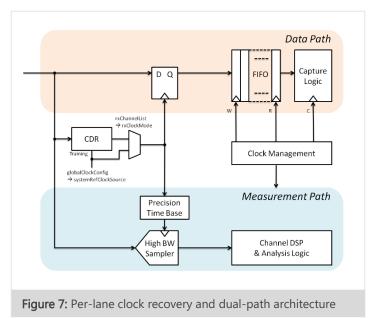


PER-LANE CLOCK RECOVERY AND UNIQUE DUAL-PATH ARCHITECTURE

Like pre-emphasis, conventional tools often require separate clock recovery instrumentation. In the SV1D, each receiver has its own embedded analog clock recovery circuit. Additionally, the clock recovery is monolithically integrated directly inside the receiver's high-speed sampler, thus offering the lowest possible sampling latency in a test and measurement instrument. The user does not have to make special connections or carefully match cable lengths. The monolithic nature of the SV1D clock recovery helps achieve wide tracking bandwidth for measuring signals that possess spread-spectrum clocking or very high amplitude wander. Figure 7 shows a block diagram of the clock recovery capability inside the SV1D Direct-Attach SerDes Module.



Also shown in Figure 7 is the dual-path receiver architecture of the SV1D. This unique architecture allows the SV1D to operate as both a digital capture/analysis instrument and an analog measurement instrument. A feature rich clock management system allows for customization of the SV1D to specific customer requirements.



AUXILIARY CONTROL PORT

The SV1D includes a low-speed auxiliary control port. It enables controlling DUT registers through JTAG, I2C, or SPI. Additionally, the port includes reconfigurable trigger and flag capabilities for synchronizing with external tools or events.



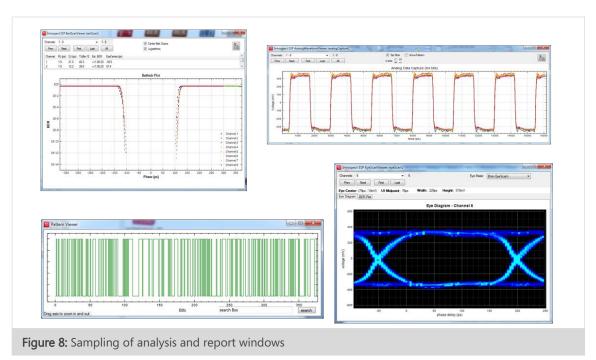
ANALYSIS

The SV1D instrument has an independent Bit Error Rate Tester (BERT) for each of its input channels. Each BERT compares recovered (retimed) data from a single input channel against a specified data pattern and reports the bit error count.

Apart from error counting, the instrument offers a wide range of measurement and analysis features including:

- Jitter separation
- Eye mask testing
- Voltage level, pre-emphasis level, and signal parameter measurement
- Frequency measurement and SSC profile extraction

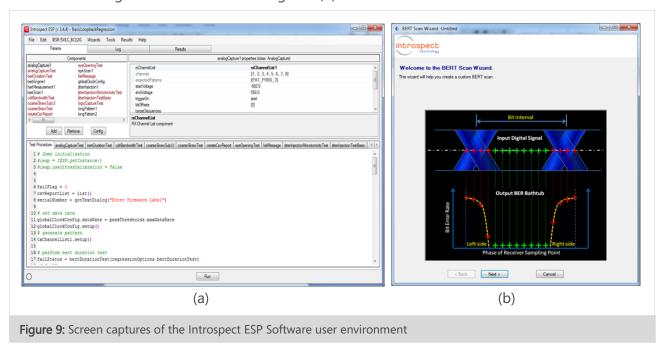
Figure 8 illustrates a few of the analysis and reporting features of the SV1D. Starting from the top left and moving in a clockwise manner, the figure illustrates bathtub acquisition and analysis, waveform capture, raw data viewing, and eye diagram plotting. As always, these analysis options are executed in parallel on all activated lanes.





AUTOMATION

The SV1D is operated using the award winning Introspect ESP Software. It features a comprehensive scripting language with an intuitive component-based design as shown in the screen shot in Figure 9(a). Component-based design is the Introspect ESP Software's way of organizing the flexibility of the instrument in a manner that allows for easy program development. It highlights to the user only the parameters that are needed for any given task, thus allowing program execution in a matter of minutes. For further help, the SV1D features automatic code generation for common tasks such as Eye Diagram or Bathtub Curve generation as shown in Figure 9(b).





Physical Description

The SV1D is supplied with a heatsink and the SV1B adaptor board. The motherboard and its connectors, standoffs and screws are to be sourced by users. The SV1D features a high-speed low profile 6x10-pin and a 40-pin (in 20 pairs) Q-Strip® connectors on the bottom side providing clock, data, SPI, JTAG control connections to the carrier motherboard. A connector on upper side provides GPIO connections to the motherboard through the included SV1B adaptor board.

Figure 10(a) illustrates the 3 connector and 4 mounting hole locations required on the motherboard. Measurements are in mil unless stated otherwise. The SV1D and SV1B boards require 2 mounting holes each for physical support. The motherboard devices should be kept away from the locations occupied by SV1D and SV1B, as shown in Figure 10(b).

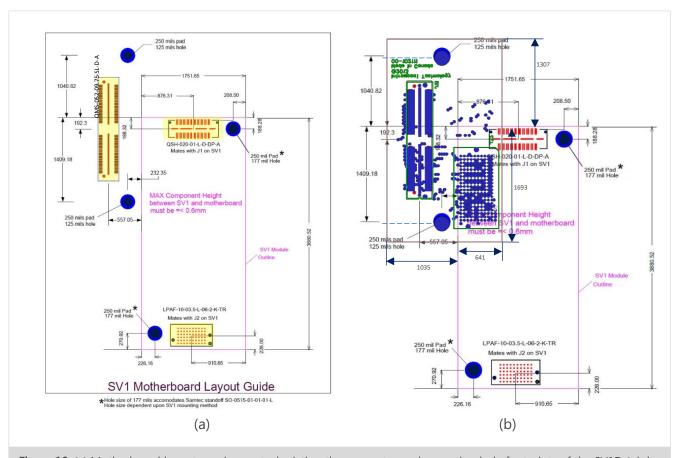


Figure 10: (a) Motherboard layout requirements depicting the connector and mounting hole footprints of the SV1D (pink outline) (b) Top view of the SV1B adaptor board location (brown outline) relative to the SV1D



The side profile of the assembled boards is shown in Figure 11, where the SV1D is mounted on the motherboard first, and then the SV1B board mounts on top of it. Please take note of the length of the standoffs needed to maintain adequate vertical clearance and tight connections among the SV1D, SV1B and the motherboard. The standoffs should be tightened by screws after assembly.

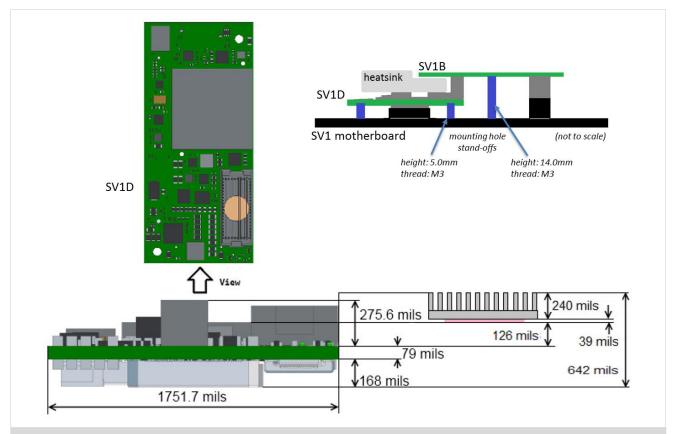


Figure 11: Top view and side profile of the SV1M showing its relief and the total height with the included heat sink. Inset figure depicts the side view of the assembled SV1B, SV1D and the motherboard.



Electrical Description

The following tables describes the pin out information of the 2 Q-strip connectors on the SV1D, and the IO connector on the motherboard. When designing the interface logic, please ensure not to drive any I/O pins on the SV1D until the power rails have been completely powered on.

TABLE 1 MOTHERBOARD J1 CONNECTOR QSH-020-01-L-D-DP-A PIN-OUT

SIGNAL	PIN LOCATION	DESCRIPTION	VOLTAGE LEVEL
12.0V	10,12,14,16,18,20,22,24, 26,28,30,32,34,36,38,40	Input Power (12.0V +/- 5% at ALL times) (Current source minimum 2A, application may demand more)	12.0V
GND	0,11,13,15,17,19,21,23, 25,27,29,31,33,35,37,39	Ground	GND
TMS	9	JTAG TMS Direct connection to FPGA	
SCLK	1	SV1D slave SPI communication port clock	
SSN	3	SV1D slave SPI communication port chip select Active low	
MOSI	5	SV1D slave SPI communication port data from master	2.57
MISO	7	SV1D slave SPI communication port data to master Open drain output	- 2.5V
TRIG1	2	Multi-purpose Trigger input	
TRIG2	4	Negative edge triggered	
FLAG1	6	Multi-purpose Flag output	
FLAG2	8	Multi-purpose Flag output	



TABLE 2 MOTHERBOARD J2 CONNECTOR LPAF-10-03.5-L-06-2-K-TR PIN-OUT

SIGNAL	PIN LOCATION	DESCRIPTION	VOLTAGE LEVEL
REFCLK_0_P,	F02, E02	External Reference Clock LVDS AC Coupled	
REFCLK_0_N	102, L02	Refer to connection diagrams	
TX8_P, TX8_N	B03, A03		
TX7_P, TX7_N	C04, B04		
TX6_P, TX6_N	B05, A05		
TX5_P, TX5_N	C06, B06	GXB Transmit Link DC coupled Programmable voltage	
TX4_P, TX4_N	B07, A07	swing	
TX3_P, TX3_N	C08, B08		
TX2_P, TX2_N	B09, A09		CVD
TX1_P, TX1_N	C10, B10		GXB
RX8_P, RX8_N	E03, D03		
RX7_P, RX7_N	F04, E04		
RX6_P, RX6_N	E05, D05		
RX5_P, RX5_N	F06, E06	GXB Receive Link DC coupled	
RX4_P, RX4_N	E07, D07	GAB Receive Link DC coupled	
RX3_P, RX3_N	F08, E08		
RX2_P, RX2_N	E09, D09		
RX1_P, RX1_N	E10, F10		
SV1_RST#	B02	Resistor divider on SV1 makes 3.3V SV1_RST# signal 2.5V compatible	3.3V
REFCLK_1_P	B01	External Reference Clock Expected to be 100MHz	2.5V LVDS
REFCLK_1_N	A01	Refer to connection diagrams	2.5G LVDS
TDO	C02	JTAG TDO Direct connection to FPGA	
TDI	E01	JTAG TDI Direct connection to FPGA	2.5V
TCK	D01	JTAG TCK Direct connection to FPGA	
GND	A02,A04,A06,A08,A10, C01,C03,C05,C07,C09, D02,D04,D06,D08,D10	Ground	GND



TABLE 3 MOTHERBOARD J4 CONNECTOR QMS-052-09.75-SL-D-A PIN-OUT

SIGNAL	PIN LOCATION	DESCRIPTION	VOLTAGE LEVEL	
PAIR00_P, PAIR00_N	1, 2	Generic IO, Programmable with Custom Firmware	2.5 V CMOS	
12.0V	3,4	Output Power (12.0V +/- 5%)	12.0V	
PAIR04_P, PAIR04_N	5, 6	LED: Lock Status, CmdProcReady	2.5V	
PAIR02_P, PAIR02_N	13, 14	LED: Lock Status, CmdProcReady	2.5V	
PAIR08_P, PAIR08_N	9, 10	Generic IO, Programmable with		
PAIR06_P, PAIR06_N	17, 18	Custom Firmware		
PAIR01_P, PAIR01_N	21, 22	LED: User LED mirror, LED: Lock		
PAIR05_P, PAIR05_N	25, 26		2.5 V CMOS	
PAIR09_P, PAIR09_N	29, 30	Generic IO, Programmable with		
PAIR03_P, PAIR03_N	33,34	Custom Firmware		
PAIR07_P, PAIR07_N	37, 38			
GND	7,8,11,12,15,16,19,20,23,24,27,28,31,32 ,35,36,39,40,43,44,47,48,51,52,55,56,59 ,60,63,64,67,68,71,72,75,76,79,80,83,84 ,87,88,91,92,95,96,99,100,	Ground	GND	
PAIR10_P, PAIR10_N	PAIR10_P, PAIR10_N 41, 42			
PAIR14_P, PAIR14_N	45, 46	Generic IO, Programmable with	2.5 V CMOS	
PAIR18_P, PAIR18_N	49, 50	Custom Firmware		
PAIR12_P, PAIR12_N 53, 54		_		
PAIR16_P, PAIR16_N	57, 58			



DAID11 D DAID11 N	61 62	I	
PAIR11_P, PAIR11_N PAIR15_P, PAIR15_N	61, 62 65, 66		
	69, 70		
PAIR19_P, PAIR19_N	73, 74		
PAIR13_P, PAIR13_N PAIR17_P_PAIR17_N	73, 74		
PAIR17_P, PAIR17_N			
PAIR20_P, PAIR20_N	81, 82	DUT manet (and a language of a	
PAIR24_P, PAIR24_N	85, 86	DUT reset (active low, driven low	
PAIR28_P, PAIR28_N	89, 90		
PAIR22_P, PAIR22_N	93, 94		
PAIR26_P, PAIR26_N	97, 98		
PAIR21_P, PAIR21_N	101, 102		
PAIR25_P, PAIR25_N PAIR29_P, PAIR29_N	105, 106 109, 110	Generic IO, Programmable with	
PAIR23_P, PAIR23_N	113, 114	Custom Firmware	
	117, 118		
PAIR27_P, PAIR27_N			
PAIR30_P, PAIR30_N	121, 122		
PAIR45_P, PAIR45_N	125, 126		
PAIR34_P, PAIR34_N	129, 130		
MGT_RX0_P, MGT_RX0_N	133, 134	Unused input, tie to Ground	
PAIR36_P, PAIR36_N	137, 138		
PAIR31_P, PAIR31_N	141, 142	Generic IO, Programmable with	
PAIR38_P, PAIR38_N	145, 146	Custom Firmware	
PAIR42_P, PAIR42_N	149, 150		
MGT_RX1_P, MGT_RX1_N	153, 154	Unused input, tie to Ground	
PAIR40_P, PAIR40_N	157, 158		
PAIR32_P, PAIR32_N	161, 162	Generic IO, Programmable with	
PAIR44_P, PAIR44_N	165, 166	Custom Firmware	
PAIR35_P, PAIR35_N	169, 170		
MGT_TX0_P, MGT_TX0_N	173, 174	Unused output, leave unconnected	
PAIR37_P, PAIR37_N	177, 178		
PAIR33_P, PAIR33_N	181, 182	Generic IO, Programmable with	
PAIR39_P, PAIR39_N	185, 186	Custom Firmware	
PAIR43_P, PAIR43_N	189, 190		
MGT_TX1_P, MGT_TX1_N	193, 194	Unused output, leave unconnected	
PAIR41_P, PAIR41_N	197, 198	Generic IO, Programmable with	



Specifications

TABLE 4 GENERAL SPECIFICATIONS

PARAMETER	VALUE	UNITS	DESCRIPTION AND CONDITIONS
Ports			
Number of Differential Transmitters	8		
Number of Differential Receivers	8		
Number of Dedicated Clock Outputs	2		Individually synthesized frequency and output format.
Number of Dedicated Clock Inputs	1		Used as external Reference Clock input.
Number of Trigger Input Pins	Multiple		Consult user manual for included capability. Contact factory for customization.
Number of Flag Output Pins	Multiple		Consult user manual for included capability. Contact factory for customization.
Data Rates and Frequencies			
Minimum Programmable Data Rate	312.5	Mbps	Contact factory for extension to lower data rates.
Maximum Programmable Data Rate	14	Gbps	
Maximum Data Rate Purchase Options	4	Gbps	
	8.5	Gbps	
	12.5	Gbps	
	14	Gbps	
Data Rate Field Upgrade	4-12.5	Gbps	Contact factory for details.
Frequency Resolution of Programmed Data Rate	1	kHz	Finer resolution is possible. Contact factory for customization.
Minimum External Input Clock Frequency	25	MHz	
Maximum External Input Clock Frequency	250	MHz	
Supported External Input Clock I/O Standards			LVDS (typical 400 mVpp input) LVPECL (typical 800 mVpp input)



TABLE 5 TRANSMITTER CHARACTERISTICS

PARAMETER	VALUE	UNITS	DESCRIPTION AND CONDITIONS
Output Coupling			
DC common mode voltage	750	mV	Typical (different offsets are firmware programmable)
AC Output Differential Impedance	100	Ohm	Typical
Voltage Performance			
Minimum Differential Voltage Swing	20	mV	
Maximum Differential Voltage Swing	1000 800	mVpp mVpp	312.5 Mbps to 5 Gbps, 50 ohm AC coupled termination. 5 Gbps to 12.5 Gbps, 50 ohm AC coupled termination.
Differential Voltage Swing Resolution	20	mV	
Accuracy of Differential Voltage Swing	larger of: +/- 10% of programmed value, and +/- 10mV	%, mV	
Rise and Fall Time	50	ps	Typical, 500 mVpp signal, 20-80%, 50 ohm AC coupled termination.
	75	ps	Typical, 500 mVpp signal, 10%-90%, 50 ohm AC coupled termination.
Pre-emphasis Performance			
Pre-Emphasis Pre-Tap Range	-4 to +4	dB	Both high-pass and low-pass functions are available. This is the smallest achievable range based on worst-case conditions. Typical operating conditions result in wider pre-emphasis range.
Pre-Emphasis Pre-Tap Resolution	Range / 32	dB	
Pre-Emphasis Post1-Tap Range	0 to 6	dB	Only high-pass function is available. This is the smallest achievable range based on worst-case conditions. Typical operating conditions result in wider pre-emphasis range.
Pre-Emphasis Post1-Tap Resolution	Range / 32	dB	



Pre-Emphasis Post2-Tap Range	-4 to +4	dB	Both high-pass and low-pass functions
Zpridolo i osta rap narige		GD.	are available. This is the smallest
			achievable range based on worst-case
			conditions. Typical operating conditions
			result in wider pre-emphasis range.
Pre-Emphasis Post2-Tap Resolution	Range / 32	dB	
Jitter Performance			
Random Jitter Noise Floor	1000	fs	Based on measurement with high-
			bandwidth scope and with first-order
			clock recovery.
Minimum Frequency of Injected Deterministic Jitter	0.1	kHz	Contact factory for further customization.
Maximum Frequency of Injected Deterministic Jitter	80	MHz	
Frequency Resolution of Injected Deterministic Jitter	0.1	kHz	Contact factory for further customization.
Maximum Peak-to-Peak Injected Deterministic Jitter	1400	ps	This specification is separate from low-
			frequency wander generator and SSC
			generator.
Magnitude Resolution of Injected Deterministic Jitter	500	fs	Jitter injection is based on multi-
			resolution synthesizer, so this number is
			an effective resolution. Internal
			synthesizer resolution is defined in
			equivalent number of bits.
Injected Deterministic Jitter Setting	Per-bank		Common across all channels within a
			bank.
Maximum RMS Random Jitter Injection	0.1	UI	
Magnitude Resolution of Injected Jitter	0.1	ps	
Accuracy of Injected Jitter Magnitude	larger of: +/-	%, ps	
	10% of		
	programmed		
	value, and		
	+/-10 ps		
Injected Random Jitter Setting	Common		Common across all channels within a
			bank.
Transmitter-to-Transmitter Skew Performance			
Lane to Lane Integer-UI Minimum Skew	-20	UI	
Lane to Lane Integer-UI Maximum Skew	20	UI	
Effect of Skew Adjustment on Jitter Injection	None		



TABLE 6 RECEIVER CHARACTERISTICS

PARAMETER	VALUE	UNITS	DESCRIPTION AND CONDITIONS
Input Coupling			
AC Input Differential Impedance	100	Ohm	
AC Performance			
Minimum Detectable Differential Voltage	25	mV	
Maximum Allowable Differential Voltage	2000	mV	
Minimum Programmable Comparator Threshold Voltage	-550	mV	
Maximum Programmable Comparator Threshold Voltage	+550	mV	
Differential Comparator Threshold Voltage Resolution	10	mV	
Differential Comparator Threshold Voltage Accuracy	larger of: +/- 10% of programmed value, and +/- 10mV	%, mV	
Measured Eye Width Accuracy	10% 15% 25%		Maximum error, 312.5 Mbps – 2.0 Gbps, 200 mVpp minimum input amplitude Maximum error, 2.0 Mbps - 5 Gbps, 200 mVpp minimum input amplitude Maximum error, 5 Gbps – 12.5 Gbps, 200 mVpp minimum input amplitude
Resolution Enhancement & Equalization	า		
DC Gain	0	dB	
	2	dB	
	4	dB	
	6	dB	
•	8	dB	
CTLE Maximum Gain	16	dB	
CTLE Resolution	1	dB	
DC Gain Control	Per-receiver		
Equalization Control	Per-receiver	1	



Input Jitter Noise Floor in System Reference Mode	25	ps	
Input Jitter Noise Floor in Extracted Clock Mode	10	ps	
Timing Generator Performance			
Resolution at Maximum Data Rate	31.25	mUI	Resolution (as a percentage of UI) improves for lower data rate. Contact factory for details.
Differential Non-Linearity Error	+/- 0.5	LSB	
Integral Non-Linearity Error	+/- 5	ps	
Range	Unlimited		
Skew			
Lane to Lane Skew Measurement Accuracy	+/- 10	ps	



TABLE 7 CLOCKING CHARACTERISTICS

PARAMETER	VALUE	UNITS	DESCRIPTION AND CONDITIONS	
Internal Time Base				
Number of Internal Frequency References	2		Relevant for future customization.	
Embedded Clock Applications				
Transmit Timing Modes	System			
	Extracted		Clock can be extracted from one of the data receiver channels in order to drive all transmitter channels.	
Receive Timing Modes	System			
	Extracted		All channels have clock recovery for extracted mode operation.	
Lane to Lane Tracking Bandwidth	4	MHz		
Single-Lane CDR Tracking Bandwidth	3 - 12	MHz		
Forwarded Clock Applications				
Transmit Timing Modes	System			
	Forwarded		Channel 1 acts as forwarded clock for samplers.	
Receive Timing Modes	System			
	Forwarded		Channel 1 acts as forwarded clock for samplers.	
Clock Tracking Bandwidth	4	MHz	Second order critically damped response.	
Spread Spectrum Support				
Receive Lanes Track SSC Data	Yes		Requires operation in extracted clock mode.	
Transmit Lanes Generate SSC Data	Yes		Consult factory for availability.	
Minimum Spread	0.1	%		
Maximum Spread	2	%		
Spread Programming Resolution	0.01	%		
Minimum Spreading Frequency	31.5	kHz		
Maximum Spreading Frequency	63	kHz		



TABLE 8 PATTERN HANDLING CHARACTERISTICS

PARAMETER	VALUE	UNITS	DESCRIPTION AND CONDITIONS
Loopback			
Rx to Tx Loopback Capability	Per channel		
Lane to Lane Latency Mismatch	0	UI	
Preset Patterns			
Standard Built-In Patterns	All Zeros		
	D21.5		
	K28.5		
	K28.7		
	50/46		
	DIV.16		
	DIV.20		
	DIV.40		
	DIV.50		
	PRBS.5		
	PRBS.7		
	PRBS.7 PRBS.9		
	PKD3.9		
	PRBS.11		
	PRBS.13		
	PRBS.15		
	PRBS.21		
	PRBS.23		
	PRBS.31		
Pattern Choice per Transmit Channel	Per-		
	transmitter		
Pattern Choice per Receive Channel	Per-receiver		
BERT Comparison Mode	Automatic		Automatically aligns to PRBS data patterns.
'	seed		
	generation		
	for PRBS		
User Programmable Pattern Memory			
Total Available Memory	2	GByte	Memory allocation is customizable. Contact
,	_	-)	factory.



Individual Force Pattern	Per-		
	transmitter		
Individual Expected Pattern	Per-receiver		
Minimum Pattern Segment Size	512	bits	
Maximum Pattern Segment Size	65536	bits	
Total Memory Space for Transmitters	1	Mbits	Memory allocation is customizable. Contact factory.
Total Expected Memory Space for Receivers	1	Mbits	Memory allocation is customizable. Contact factory.
Pattern Sequencing			
Sequence Control	Loop infinite		
	Loop on		
	count		
	Play to end		
Number of Sequencer Slots per Pattern Generator	4		This refers to the number of sequencer slots that can operate at any given time. The instrument
Generator			has storage space for 16 different sequencer
			programs.
Maximum Loop Count per Sequencer Slot	216 - 1		
Additional Pattern Characteristics			
Pattern Switching	Wait to end		When sourcing PRBS patterns, this option does
-	of segment		not exist.
	Immediate		
Raw Data Capture Length	8192	bits	



TABLE 9 MEASUREMENT AND THROUGHPUT CHARACTERISTICS

PARAMETER	VALUE	UNITS	DESCRIPTION AND CONDITIONS
BERT Sync			
Alignment Modes	Pattern		Module can align to any user pattern or preset pattern.
	PRBS		
Minimum SYNC Error Threshold	3	bits	
Maximum SYNC Error Threshold	232-1	bits	
Minimum SYNC Sample Count	1024	bits	
Maximum SYNC Sample Count	232	bits	
SYNC Time	20	ms	Assumes a PRBS7 pattern that is stored in a user pattern segment and worst-case misalignment between DUT pattern and expected pattern; data rate is 3.25 Gbps.
BERT			
Error Counter Size	32	bits	Sample counts in the BERT are programmed in increments of 32 bits.
Maximum Single-Shot Duration	232-1	bits	Repeat mode is available to continuously count over longer durations.
Continuous Duration	Indefinite		
Alignment			
CDR Lock Time	5	us	
Self-Alignment Time	50	ms	



TABLE 10 INSTRUCTION SEQUENCE CACHE

PARAMETER	VALUE	UNITS	DESCRIPTION AND CONDITIONS	
Simple Instruction Cache				
Instruction Learn mode Instruction	Start			
	Stop			
	Replay			
Advanced Instruction Cache				
Local Instruction Storage	1M			
_	Instructions			
Instruction Sequence Segments	1000			

TABLE 11 DUT CONTROL CAPABILITIES

PARAMETER	VALUE	UNITS	DESCRIPTION AND CONDITIONS	
DUT IEEE-1149-1 (JTAG) Port (Option)				
JTAG-Port Transmit Signals	TCK			
	TRST			
	TDI			
JTAG-Port Receive Signals	TDO			
JTAG-Port Transmit Voltage Swing (Fixed)	0 to 2.5	V		
JTAG-Port Receive Max Voltage Swing	0 to 2.5	V		
TDI Bit Memory	4k			
TDO Bit Memory	4k			
DUT SPI Port (Option)				
SPI Signals	SCLK			
	SSN			
	MISO			
	MOSI			
Voltage Swing (Fixed)	0 to 2.5	V		



REVISON NUMBER	HISTORY	DATE
1.0	Document release	Feb 27, 2013
1.1	Updated jitter injection specs, SSC specs, clock recovery specs; added block diagram descriptions	Oct 07, 2013
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1.3	Update to specifications	Nov 12, 2013
1.4	Update to specifications	Apr 15, 2014
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1.7	Updated document template	December 6, 2022

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